Foundation of Machine Learning (CSE4032) Lecture 03: Simple and Multiple Linear Regression

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Introduction

- In statistics, linear regression is a linear approach to modeling the relationship between a scalar response (or dependent variable) and one or more explanatory variables (or independent variables).
- Linear regression is a linear model, e.g. a model that assumes a linear relationship between the input variables (X) and the single output variable (y). More specifically, that y can be calculated from a linear combination of the input variables (X).
- When there is a single input variable (X), the method is referred to as simple linear regression; however, when there are multiple input variables, literature from statistics often refers to the method as multiple linear regression.

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Simple Linear Regression Model

Simple Linear Regression

- It is a very straightforward simple linear approach for predicting a quantitative response Y on the basis of a single variable X.
- It assumes that there is approximately a linear relationship between X and Y.
 Mathematically, we can write this linear relationship as

 $Y \approx \beta_0 + \beta_1 X$

• For example, X may represent TV advertising and Y may represent sales. Then we can regress sales onto TV by fitting the model

sales $\approx \beta_0 + \beta_1 \times \text{TV}.$

Here, β₀ and β₁ are two unknown constants that represent the intercept and slope terms in the linear model. Together, β₀ and β₁ are intercept-slope known as the model coefficients or parameters.



Simple regression model

 If we can estimate the model coefficients, β̂₀ and β̂₁, using the training data then we can predict future sales on the basis of a particular value of TV advertising by computing

$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x$$

where \hat{y} indicates a prediction of Y on the basis of X = x.

- Estimating the Coefficients
 - □ Let $(x_1, y_1), (x_2, y_2), \ldots, (x_n, y_n)$ represent *n* observation pairs, each of which consists of a measurement of *X* and a measurement of *Y*.
 - \Box Our goal is to obtain coefficient estimates $\hat{\beta}_0$ and $\hat{\beta}_1$ such that the linear model fits the available data well—that is, so that $y_i \approx \hat{\beta}_0 + \hat{\beta}_1 x_i$ for $i = 1, \ldots, n$.
- Most common approach involves minimizing the least squares criterion.

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Simple regression model



- Let ŷ_i = β̂₀ + β̂₁x_i be the prediction for Y based on the *i*th value of X.
- Then $e_i = y_i \hat{y}_i$ represents the *i*th residual
- This is the difference between the *i*th observed response value and the *i*th response value that is predicted by our linear model.
- We define the residual sum of squares (RSS) as

$$\left(\text{RSS} = e_1^2 + e_2^2 + \dots + e_n^2 \right)$$

Simple regression model

or equivalently as

RSS =
$$(y_1 - \hat{\beta}_0 - \hat{\beta}_1 x_1)^2 + (y_2 - \hat{\beta}_0 - \hat{\beta}_1 x_2)^2 + \ldots + (y_n - \hat{\beta}_0 - \hat{\beta}_1 x_n)^2$$

- The least squares approach chooses $\hat{\beta}_0$ and $\hat{\beta}_1$ to minimize the RSS.
- Using some calculus, one can show that the minimizers are

$$\hat{\beta}_{1} = \frac{\sum_{i=1}^{n} (x_{i} - \bar{x}) (y_{i} - \bar{y})}{\sum_{i=1}^{n} (x_{i} - \bar{x})^{2}}$$
$$\hat{\beta}_{0} = \bar{y} - \hat{\beta}_{1} \bar{x}$$

where $\bar{y} \equiv \frac{1}{n} \sum_{i=1}^{n} y_i$ and $\bar{x} \equiv \frac{1}{n} \sum_{i=1}^{n} x_i$ are the sample means.

 Above equation defines the least squares coefficient estimates for simple linear regression.

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Multiple Linear Regression Model

- A linear regression model assumes that the regression function E(Y|X) is linear in the inputs X_1, \ldots, X_p .
- They are simple and often provide an adequate and interpretable description of how the inputs affect the output.
- An understanding of linear methods is essential for understanding nonlinear ones.
- In fact, many nonlinear techniques are direct generalizations of the linear methods discussed here.

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• Suppose, we have an input vector $X^T = (X_1, X_2, \dots, X_p)$ and want to predict a real-valued output Y. The linear regression model has the form

$$f(X) = \beta_0 + \sum_{j=1}^p X_j \beta_j$$

- The linear model either assumes that the regression function $E(Y \mid X)$ is linear, or that the linear model is a reasonable approximation.
- Here, the β_j's are unknown parameters or coefficients, and the variables X_j can come from different sources.

- The variable X_j can come from different sources
 - Quantitative inputs
 - □ Transformation of quantitative i/p, for e.g., log, square root, square, exp, etc.
 - $\hfill\square$ Basic expansion, $X_2=X_1^2, X_3=X_1^3$ leading to a polynomial representation.
 - Numeric or dummy coding of the levels of qualitative i/p.
 - □ Interaction between variables, e.g., $X_3 = X_1 \cdot X_2$.
- No matter the source of the X_j , the model is linear in the parameters.

- Typically, we have a set of training data (x₁, y₁)...(x_N, y_N) from which to estimate the parameters β.
- Each $x_i = (x_{i1}, x_{i2}, \dots, x_{ip})^T$ is a vector of feature measurements for the *i*th case.
- The most popular estimation method is least squares, in which we pick the coefficients $\beta = (\beta_0, \beta_1, \dots, \beta_p)^T$ to minimize the residual sum of squares

$$\operatorname{RSS}(\beta) = \sum_{i=1}^{N} (y_i - f(x_i))^2$$
$$= \sum_{i=1}^{N} \left(y_i - \beta_0 - \sum_{j=1}^{p} x_{ij} \beta_j \right)^2$$

• Criteria measures the avaerage lack of fit.

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- From a statistical point of view, this criterion is reasonable if the training observations (x_i, y_i) represent independent random draws from their population. Even if the x_i 's were not drawn randomly, the criterion is still valid if the y_i 's are conditionally independent given the inputs x_i .
- How to minimize the criteria function?

$$X \to N \times (p+1)$$

$$Y \to N \times 1$$

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Then we can write

$$\operatorname{RSS}(\beta) = (\mathbf{y} - \mathbf{X}\beta)^T (\mathbf{y} - \mathbf{X}\beta)^T$$

 \blacksquare Differentiating w.r.t β we get

$$\frac{\partial \operatorname{RSS}}{\partial \beta} = -2\mathbf{X}^T (\mathbf{y} - \mathbf{X}\beta)$$
$$\frac{\partial^2 \operatorname{RSS}}{\partial \beta \partial \beta^T} = 2\mathbf{X}^T \mathbf{X}$$

Assuming (for the moment) that X has full column rank, and hence X^TX is positive definite, we set the first derivative to zero

$$\mathbf{X}^{T}(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) = 0 \tag{1}$$

• Then, we obtain the unique solution

$$\hat{eta} = \left(\mathbf{X}^T \mathbf{X}
ight)^{-1} \mathbf{X}^T \mathbf{y}$$

The predicted values at an input vector x₀ are given by f̂ (x₀) = (1 : x₀)^T β̂; the fitted values at the training inputs are

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}} = \mathbf{X} \left(\mathbf{X}^T \mathbf{X}\right)^{-1} \mathbf{X}^T \mathbf{y}$$

where $\hat{y}_i = \hat{f}(x_i)$.

The matrix H = X (X^TX)⁻¹ X^T is sometimes called the "hat" matrix because it puts the hat on y.



- We minimize RSS(β) = ||y Xβ||² by choosing β̂ so that the residual vector y ŷ is orthogonal to this subspace. This orthogonality is expressed in Eq. (1), and the resulting estimate ŷ is hence the orthogonal projection of y onto this subspace.
- The hat matrix *H* computes the orthogonal projection, and hence it is also known as a projection matrix.
- If the columns of X are not linearly independent, so that X is not of full rank.
 For example, if two of the inputs were perfectly correlated, (e.g., x₂ = 3x₁).
 Then X^TX is singular and the least squares coefficients β are not uniquely defined.
- However, the fitted values ŷ = Xβ̂ are still the projection of y onto the column space of X; there is just more than one way to express that projection in terms of the column vectors of X.

- Rank deficiencies can also occur in signal and image analysis, where the number of inputs p can exceed the number of training cases N. In this case, the features are typically reduced by filtering or else the fitting is controlled by regularization.
- Up to now we have made minimal assumptions about the true distribution of the data. Sampling properties of β̂ assume y_i are uncorrelated and have constant variance σ², and that the x_i are fixed (non random).

$$\operatorname{Var}(\hat{\beta}) = \left(\mathbf{X}^T \mathbf{X}\right)^{-1} \sigma^2$$

Typically one estimates the variance σ^2 by

$$\hat{\sigma}^2 = \frac{1}{N-p-1} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2.$$

Multiple regression model: drawn inference

• We assume as $Y = f(x) = \beta_0 + \sum_{i=1}^n X_j \beta_j$ is correct model, that means

$$Y = \mathbb{E} \left(Y \mid X_1, \dots, X_p \right) + \varepsilon$$
$$= \beta_0 + \sum_{j=1}^p X_j \beta_j + \varepsilon$$

- where the error ε is a Gaussian random variable with expectation zero and variance σ^2 , written $\varepsilon \sim N\left(0,\sigma^2\right)$.
- It is easy to show that

$$\hat{\boldsymbol{\beta}} \sim N\left(\boldsymbol{\beta}, \left(\mathbf{X}^T \mathbf{X}\right)^{-1} \sigma^2\right)$$

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- The linear model with p > 1 inputs is called the multiple linear regression model.
- Suppose first that we have a univariate model with no intercept, that is,

 $Y = X\beta + \epsilon$

• The least squares estimate and residuals are

$$\hat{\beta} = \frac{\sum_{1}^{N} x_i y_i}{\sum_{1}^{N} x_i^2}$$
$$r_i = y_i - x_i \hat{\beta}$$

In convenient vector notation, we let $\mathbf{y} = (y_1, \dots, y_N)^T$, $\mathbf{x} = (x_1, \dots, x_N)^T$ and define

$$egin{aligned} &\langle \mathbf{x}, \mathbf{y}
angle &= \sum_{i=1}^{T} x_i y_i, \ &= \mathbf{x}^T \mathbf{y} \end{aligned}$$

the inner product between ${\bf x}$ and ${\bf y}.$

Then we can write

$$\hat{\beta} = \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\langle \mathbf{x}, \mathbf{x} \rangle}$$
$$\mathbf{r} = \mathbf{y} - \mathbf{x} \hat{\beta}$$

This simple univariate regression provides the building block for multiple linear regression.

Suppose next that the inputs x₁, x₂,..., x_p (the columns of the data matrix X) are orthogonal; that is

$$\langle \mathbf{x}_j, \mathbf{x}_k
angle = 0$$
 for all $j \neq k$.

- Then it is easy to check that the multiple least squares estimates
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 _j are equal to (x_j, y) / (x_j, x_j) the univariate estimates.
- In other words, when the inputs are orthogonal, they have no effect on each other's parameter estimates in the model.
- Orthogonal inputs occur most often with balanced, designed experiments (where orthogonality is enforced), but almost never with observational data.
- Hence, we will have to orthogonalize them in order to carry this idea further.



Suppose next that we have an intercept and a single input x. Then the least squares coefficient of x has the form

$$\hat{\beta}_1 = rac{\langle \mathbf{x} - \bar{x} \mathbf{1}, \mathbf{y} \rangle}{\langle \mathbf{x} - \bar{x} \mathbf{1}, \mathbf{x} - \bar{x} \mathbf{1} \rangle}$$

where $\bar{x} = \sum_i x_i / N$, and $\mathbf{1} = \mathbf{x}_0$, the vector of N ones.

- We can view the estimate of
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 - 1. regress x on 1 to produce the residual $z = x \bar{x}1$;
 - 2. regress y on the residual z to give the coefficient $\hat{\beta}_1$.
- In this procedure, "regress **b** on **a**" means a simple univariate regression of **b** on **a** with no intercept, producing coefficient $\hat{\gamma} = \langle \mathbf{a}, \mathbf{b} \rangle / \langle \mathbf{a}, \mathbf{a} \rangle$ and residual vector $\mathbf{b} \hat{\gamma}\mathbf{a}$. We say that **b** is adjusted for **a**, or is "orthogonalized" with respect to **a**.

- Step 1 orthogonalizes \mathbf{x} with respect to $\mathbf{x}_0 = \mathbf{1}$.
- Step 2 is just a simple univariate regression, using the orthogonal predictors 1 and z.



Note that the inputs z₀,..., z_{j-1} in step 2 are orthogonal, hence the simple regression coefficients computed there are in fact also the multiple regression coefficients. The result of this algorithm is

$$\hat{eta}_p = rac{\langle \mathbf{z}_p, \mathbf{y} \rangle}{\langle \mathbf{z}_p, \mathbf{z}_p \rangle}$$
 (2)

Stated more generally, the *j*th multiple regression coefficient is the univariate regression coefficient of y on x_{j·012...(j-1)(j+1)...p}, the residual after regressing x_j on x₀, x₁,..., x_{j-1}, x_{j+1},..., x_p : The multiple regression coefficient β_j represents the additional contribution of x_j on y, after x_j has been adjusted for x₀, x₁,..., x_{j-1}, x_{j+1},..., x_p

From (2), we also obtain an alternate formula for the variance estimates:

$$\operatorname{Var}\left(\hat{\beta}_{p}\right) = \frac{\sigma^{2}}{\left\langle \mathbf{z}_{p}, \mathbf{z}_{p} \right\rangle} = \frac{\sigma^{2}}{\left\|\mathbf{z}_{p}\right\|^{2}}$$

In other words, the precision with which we can estimate \(\beta_p\) depends on the length of the residual vector \(\mathbf{z}_p\); this represents how much of \(\mathbf{x}_p\) is unexplained by the other \(\mathbf{x}_k\)'s.

- Above discussed Algorithm is known as the Gram–Schmidt procedure for multiple regression, and is also a useful numerical strategy for computing the estimates.
- We can represent step 2 of the Algorithm in matrix form:

 $\mathbf{X} = \mathbf{Z} \Gamma$

where Z has as columns the z_j (in order), and Γ is the upper triangular matrix with entries $\hat{\gamma}_{kj}$.

• Introducing the diagonal matrix **D** with *j*th diagonal entry $D_{jj} = ||\mathbf{z}_j||$, we get

 $\mathbf{X} = \mathbf{Z}\mathbf{D}^{-1}\mathbf{D}\Gamma$ $= \mathbf{Q}\mathbf{R}$

the so-called QR decomposition of X. Here Q is an $N \times (p+1)$ orthogonal matrix, $\mathbf{Q}^T \mathbf{Q} = \mathbf{I}$, and R is a $(p+1) \times (p+1)$ upper triangular matrix. The QR decomposition represents a convenient orthogonal basis for the column space of X. It is easy to see, for example, that the least squares solution is given by

$$\hat{\boldsymbol{\beta}} = \mathbf{R}^{-1} \mathbf{Q}^T \mathbf{y}, \\ \hat{\mathbf{y}} = \mathbf{Q} \mathbf{Q}^T \mathbf{y}$$
(3)

Equation (3) is easy to solve because \mathbf{R} , is upper triangular.

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Thank you!